

# MULTI-UNIT DASSYSTEM

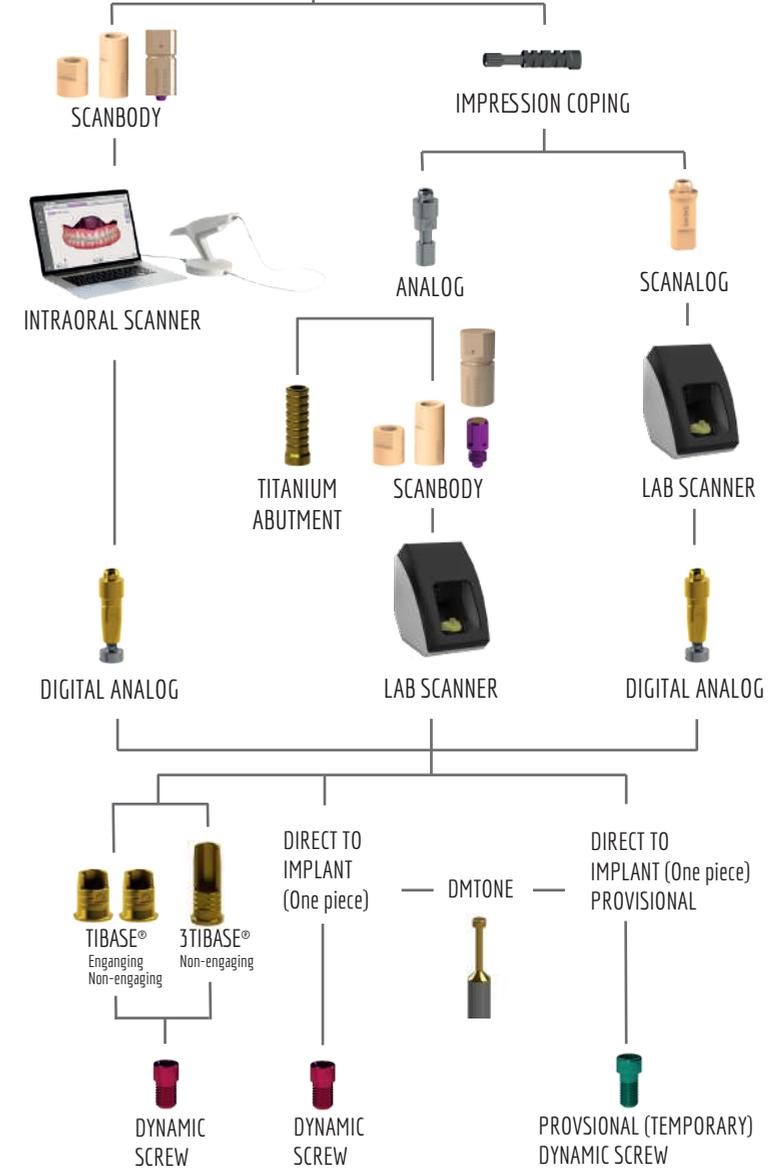
Work different, work better



DYNAMIC ABUTMENT\* SOLUTIONS

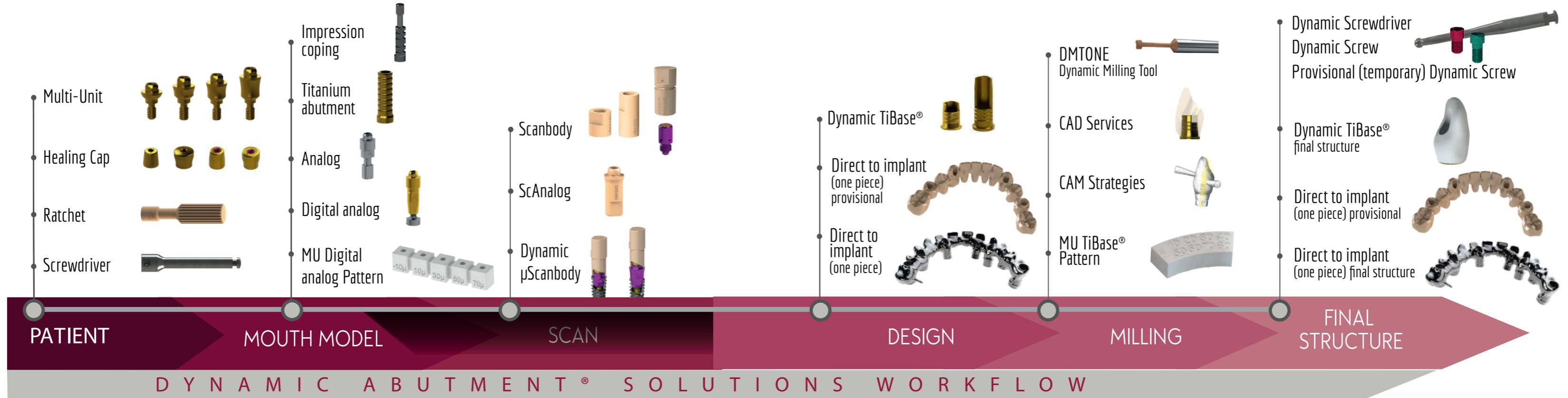
# MULTI-UNIT DASSYSTEM

Work different, work better



Digital workflow from the beginning to the end of the work. With both intraoral and lab scanners. Also available with full analogue workflow.

DIGITAL WORKFLOW - MULTI-UNIT DAS SYSTEM



Implant planning

DAS Libraries:  
**exoplan**

Plaster model      Printed 3D model      Milled model      Transfer impression

Lab Scanner      Intraoral Scanner

CAD design

DAS libraries:  
3shape  
exocad  
dental wings

Milling CAM

DAS tested CAM software:  
**worknc** Dental  
**hyperDENT**  
**FOLLOW-ME 1** TECHNOLOGY GROUP  
**sum3** MILL BOX  
**GO2dental**  
**vhf**

# MULTI-UNIT

The Multi-unit abutment has been carefully designed to rehabilitate partially or fully edentulous arches, as well as individual.

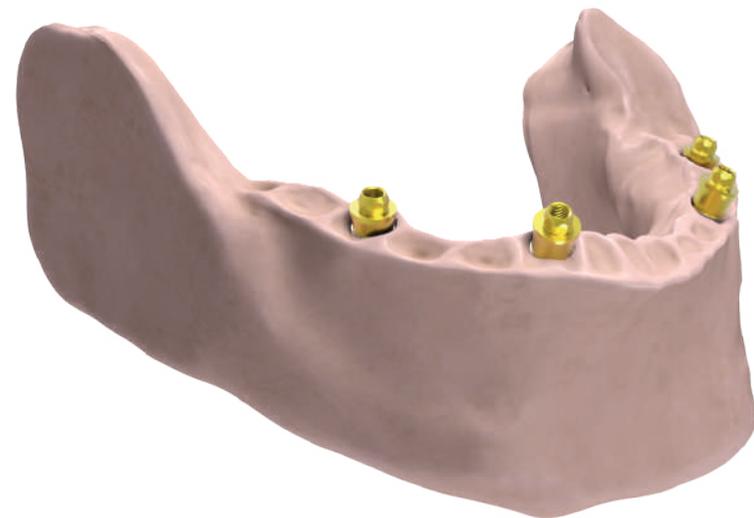
Maximum diameter of the MU is 4mm, being narrower it avoids contact with the bone



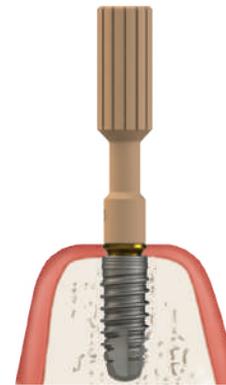
Lower cone height which allows greater disparelism than the classic multi-unit.  
Divergence between implants: 50°

Concave design facilitates healing and soft tissue adaptation.

Available in 4 gingival heights.

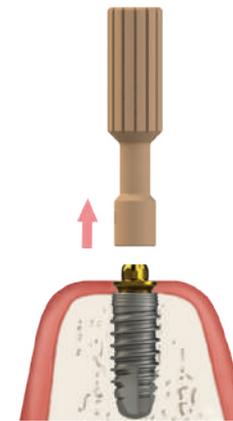


## MU Insertion Procedure



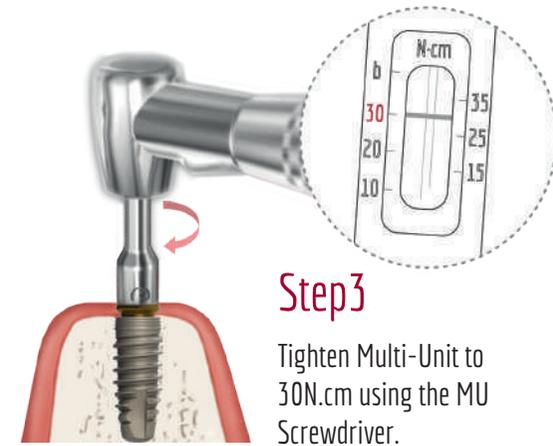
### Step1

Use the plastic gripping tool to attach the Multi-Unit to the implant.



### Step2

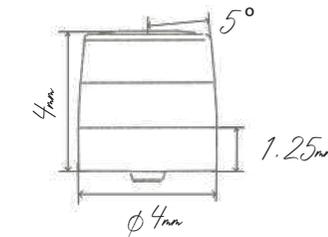
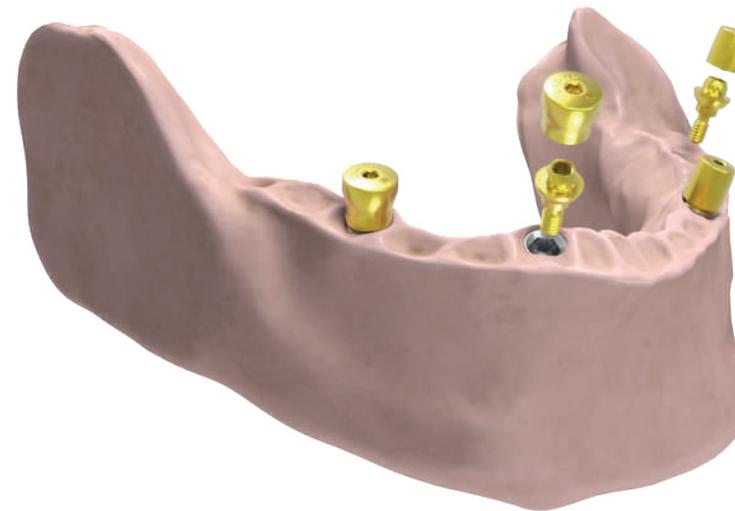
Remove the plastic tool.



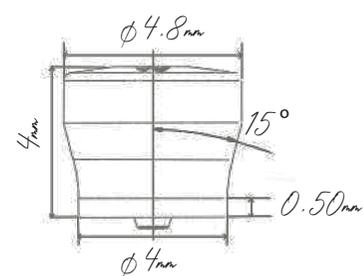
### Step3

Tighten Multi-Unit to 30N.cm using the MU Screwdriver.

## MU Healing Caps

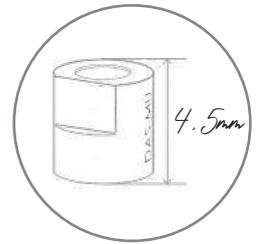


Healing cap Regular

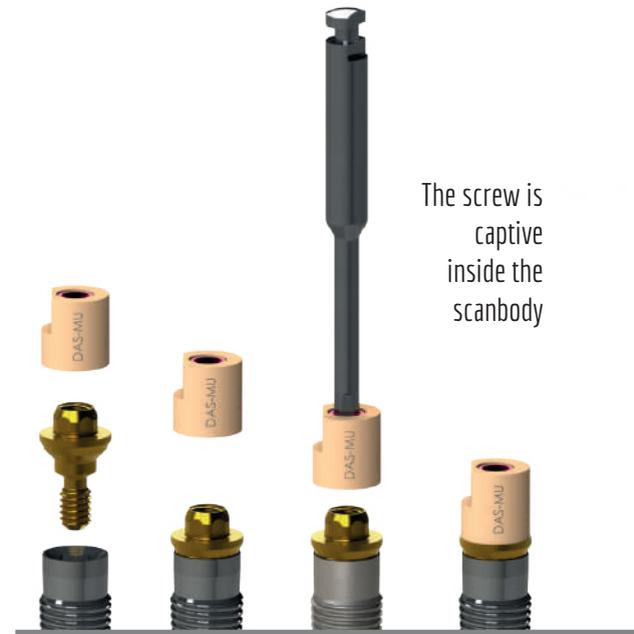
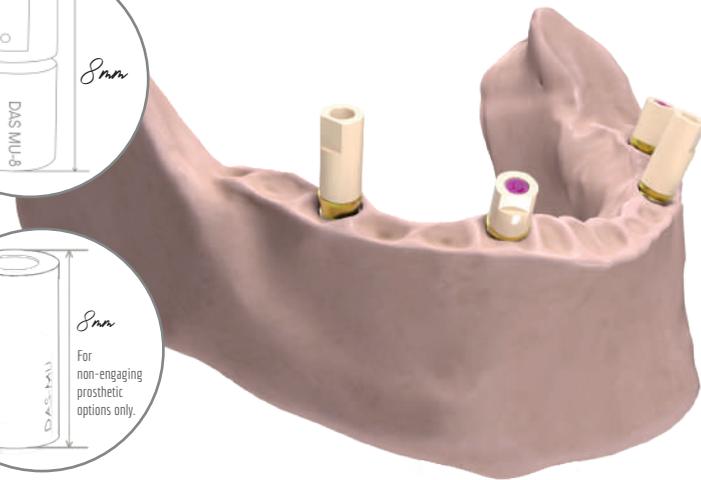


Healing cap Wide

# MULTI-UNIT SCANBODY



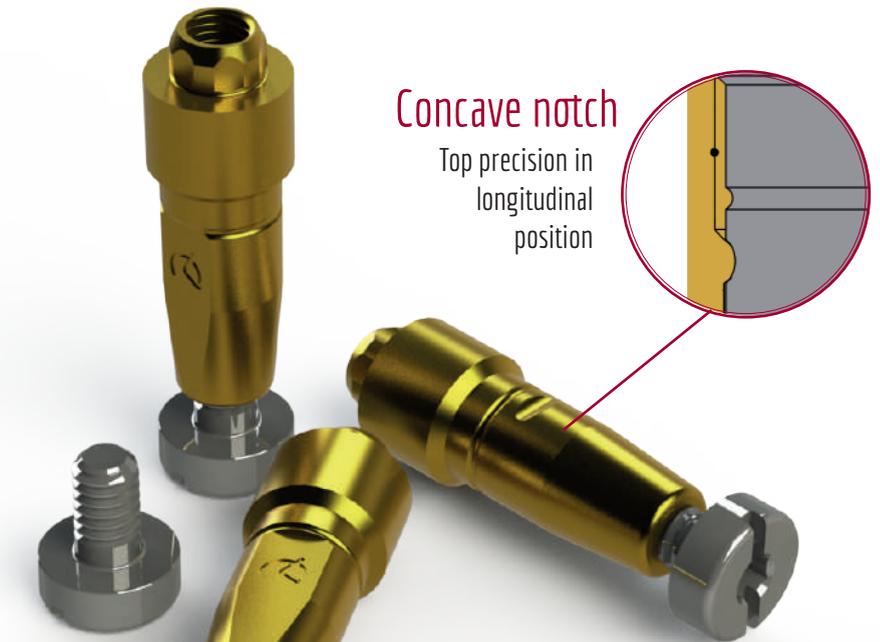
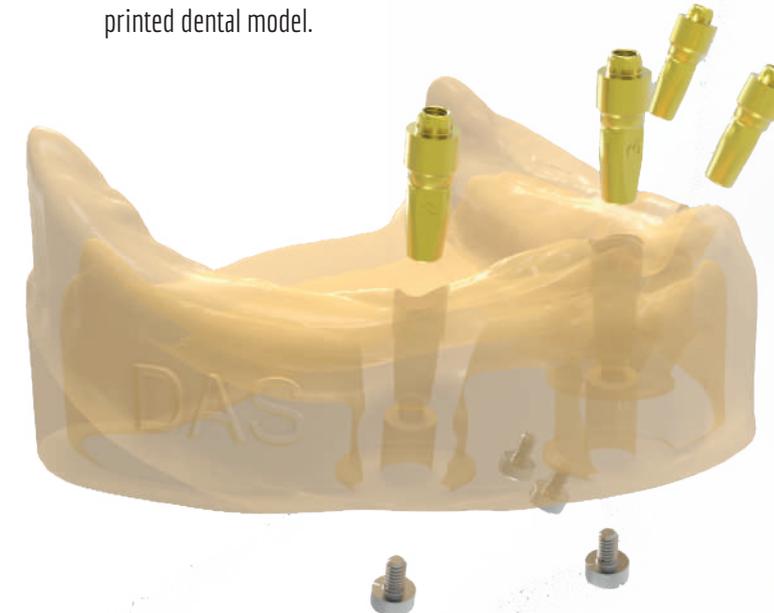
3 different scanbodies available in order to choose in which situation is better to use 4,5mm, 8mm or Dynamic  $\mu$ Scanbody with magnet system.



The screw is captive inside the scanbody

# DIGITAL ANALOG

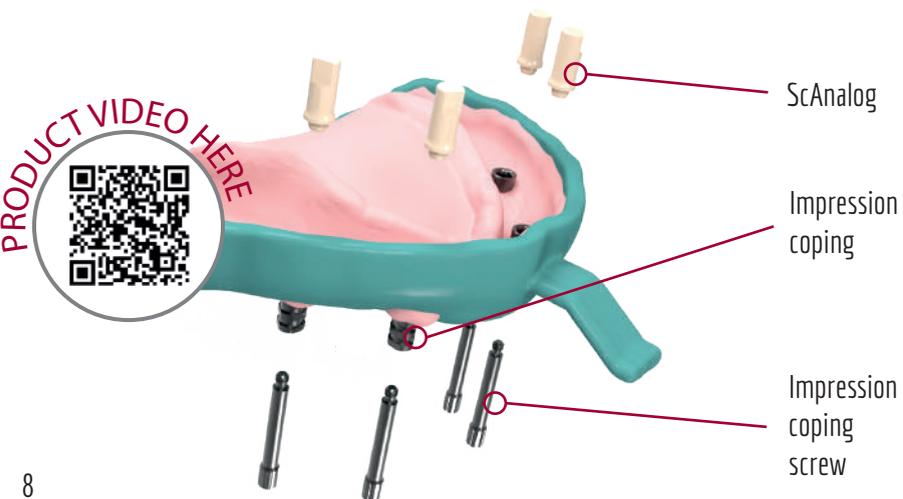
Digital analog of the dental implant to simulate implant position in a 3D printed dental model.



**Concave notch**  
Top precision in longitudinal position

**Screwed fastening**  
Prevents the analog from moving in Z

# MULTI-UNIT SCANALOG



ScAnalog

Impression coping

Impression coping screw

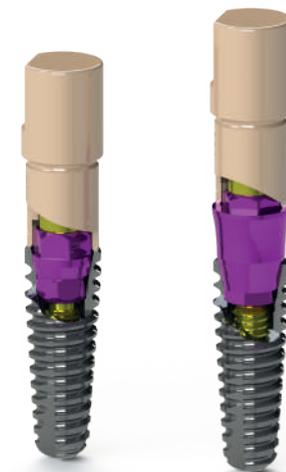


# DYNAMIC $\mu$ SCANBODY

All components of the Multi-Unit DAS System can also be used with the Dynamic  $\mu$ Scanbody to scan direct to implant and select virtually the ideal gingival height Multi-unit.

You can scan with the Dynamic  $\mu$ Scanbody and then use the special Dynamic  $\mu$ Scanbody library with the MU components.

For non-engaging prosthetic options only.



# ANALOG

Also available traditional analog for plaster model.



**Curved Surface**  
Accuracy of orientation guaranteed

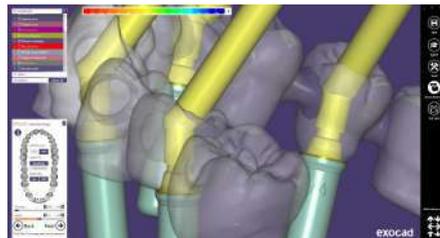
**Longitudinal cut**  
Longitudinal cut to avoid rotation X-Y

# DYNAMIC TIBASE®

To correct **ANGULATION** up to **45°**

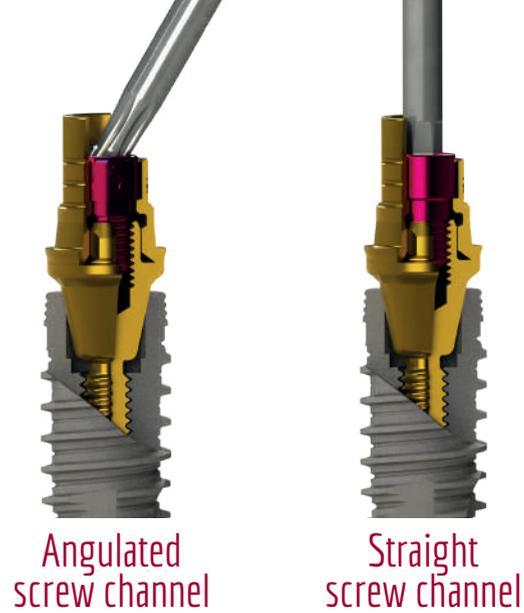


## CAD DESIGN



3shape  
exocad  
dental.wings

DAS Multi-U nit system **allows to change** the **MU** in the **library** without rescanning or redesigning the case. That facilitates the lab and clinic work, as technician can change the MU without the need to make a new appointment with the patient to re-scan.  
**If we make a NR case, the option of changing MU is not allow in the design.**



Angulated screw channel

Straight screw channel

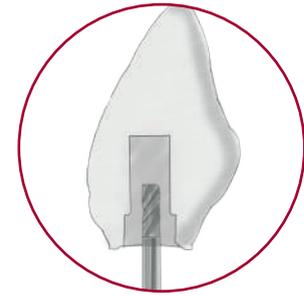


TIBASE®  
NON-ENGAGING  
ENGAGING



3TIBASE®  
NON-ENGAGING

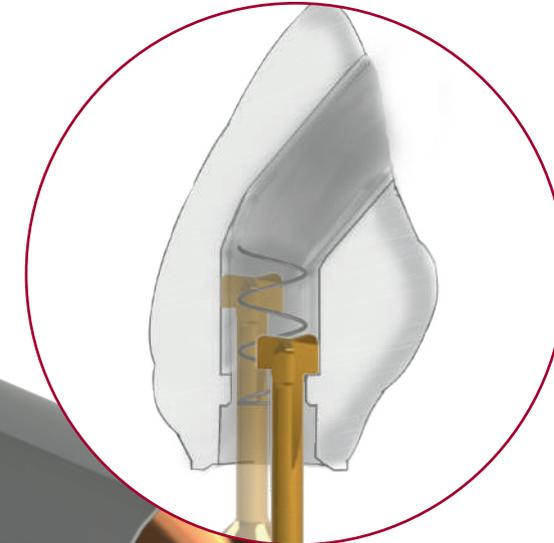
# DIRECT TO IMPLANT (One piece)



Step 1  
Crown with pre drill



Step 2  
Crown with angled channel



Step 3  
DMTONE

Crown with Dynamic Milling Tool. Milling the screw seat and increasing the diameter of the straight channel.



Dynamic screw



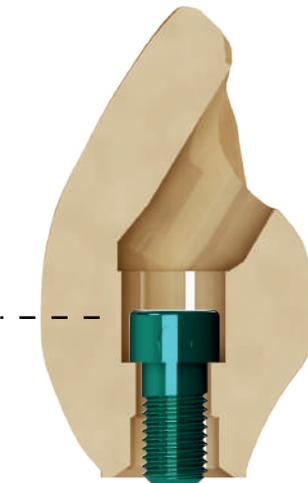
Provisional (temporary) Dynamic screw

Greater seating thickness  
Greater contact surface between the screw and the material for greater safety in soft materials.



Final restorations 0-45°

Direct to implant libraries available R/NR



Provisional (temporary) restorations up to 35°

Provisional (temporary) Direct to implant libraries available R/NR

# DAS MU LIBRARIES

## DAS MU PREMIUM library



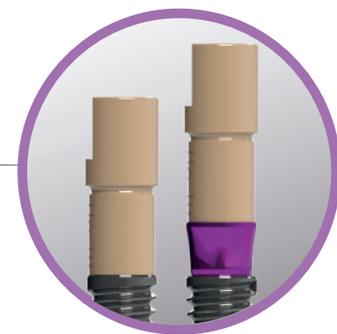
### MU Scanbody

DAS\_MU\_4.5\_XXXX\*\_PREMIUM  
 DAS\_MU\_8\_XXXX\*\_PREMIUM  
 DAS\_MU\_DS8\_XXXX\*\_PREMIUM



### MU ScAnalog

DAS\_MU\_SA\_XXXX\*\_PREMIUM



### Dynamic μScanbody

DAS\_MU\_I/IG\_XXXX\*\_PREMIUM

\*XXXX= compatibility code

# MU DAS SYSTEM COMPONENTS



Ratchet  
 49.409.000.01-2



Screwdriver  
 43.321.316.01-2



Healing Cap Regular  
 40.320.003.98-2  
 40.320.003.88-2 (Captive screw)



Healing Cap Wide  
 40.320.003.99-2  
 40.320.003.89-2 (Captive screw)



Impression coping  
 29.301.000.10-2 (Engaging)  
 29.301.000.11-2 (Non-engaging)



Analog  
 22.612.209.01-2



Titanium Abutment  
 35.312.209.21-2



Digital Analog  
 34.312.209.01-2



MU Scanbody 4,5mm  
 53.412.209.01-2



MU Scanbody 8mm  
 53.422.209.02-2 (R)



MU Dynamic μScanbody  
 52.418.137.01-2



Screwdriver adaptor  
 43.621.410.01-2  
 43.624.410.01-2  
 43.630.410.01-2



MU ScAnalog  
 23.412.209.01-2



MU Dynamic TiBase®  
 31.312.209.01-2 (Engaging)



31.322.209.01-2 (Non-engaging)



MU Dynamic 3TiBase®  
 31.322.209.21-2 (Non-engaging)



Dynamic Screw  
 41.320.040.01-2



Provisional (temporary)  
 Dynamic Screw  
 41.320.050.02-2



Straight Screw  
 40.320.003.06-2



Dynamic Screwdriver  
 43.618.201.01-2 (18mm)  
 43.624.201.01-2 (24mm)  
 43.632.201.01-2 (32mm)



Screwdriver Hex.1,2  
 43.601.103.02-2



MU DMTone  
 33.390.716.01-2 Shank Ø3  
 33.490.716.01-2 Shank Ø4  
 33.690.716.01-2 Shank Ø6