

# MULTI-UNIT DASSYSTEM

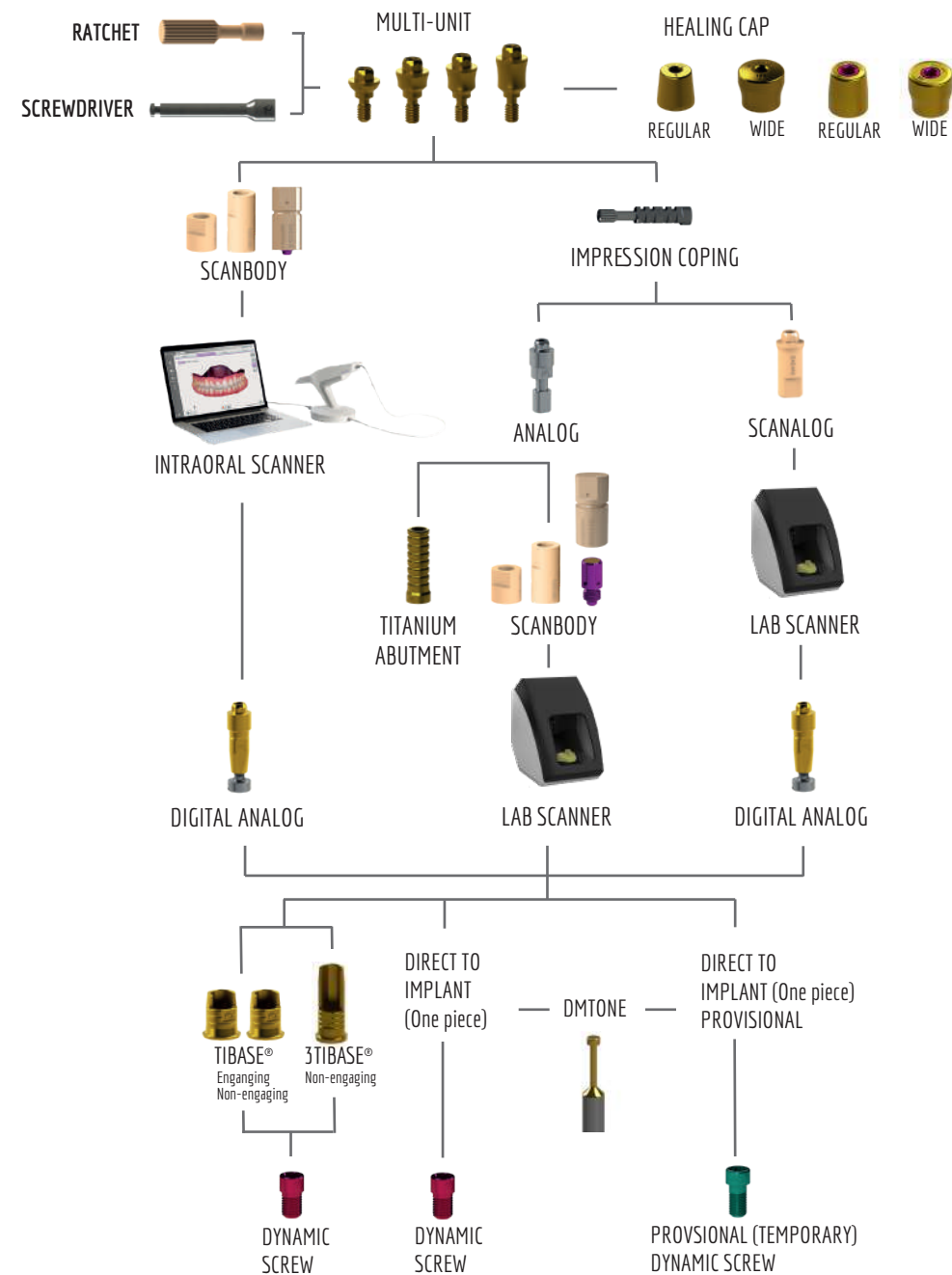
Work different, work better



DYNAMIC ABUTMENT® SOLUTIONS

# MULTI-UNIT DASSYSTEM

Work different, work better



Digital workflow from the beginning to the end of the work. With both intraoral and lab scanners. Also available with full analogue workflow.

DIGITAL WORKFLOW - MULTI-UNIT DAS SYSTEM



# MULTI-UNIT

The Multi-unit abutment has been carefully designed to rehabilitate partially or fully edentulous arches, as well as individual.

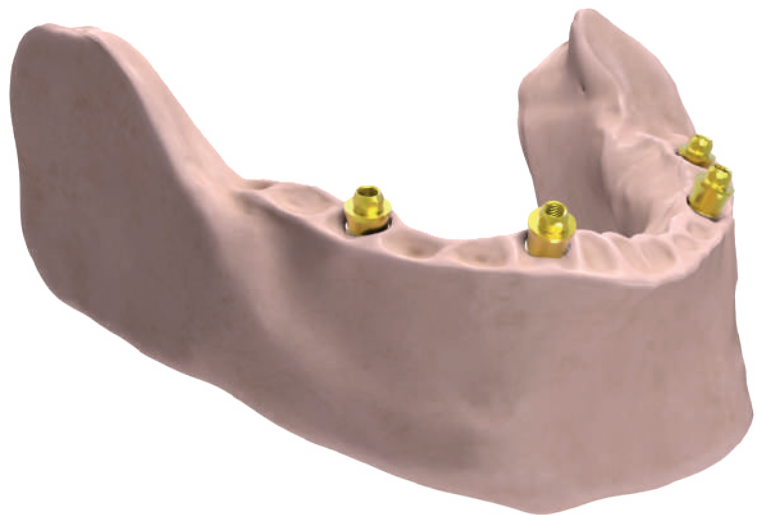
Maximum diameter of the MU is 4mm, being narrower it avoids contact with the bone



Lower cone height which allows greater disparelism than the classic multi-unit.  
Divergence between implants: 50°

Concave design facilitates healing and soft tissue adaptation.

Available in 4 gingival heights.



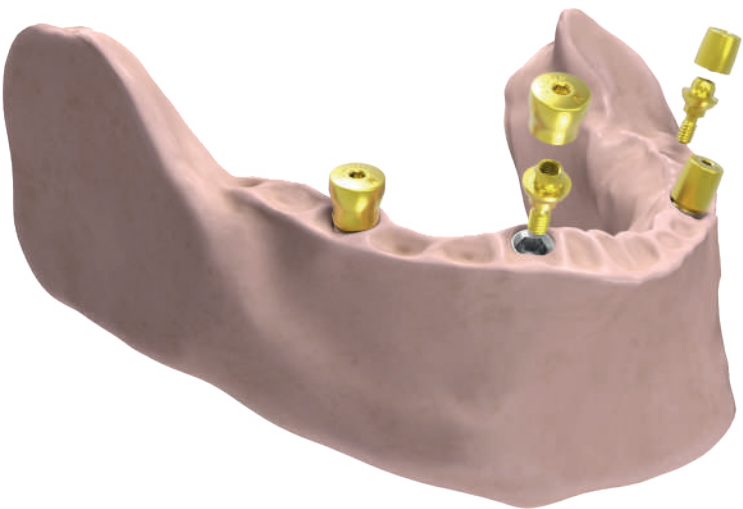
## MU Insertion Procedure

**Step1**  
Use the plastic gripping tool to attach the Multi-Unit to the implant.

**Step2**  
Remove the plastic tool.

**Step3**  
Tighten Multi-Unit to 30N.cm using the MU Screwdriver.

## MU Healing Caps



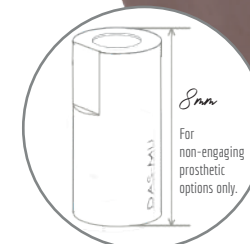
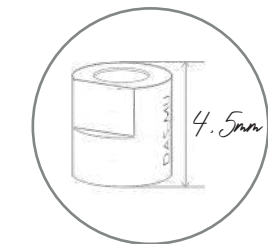
4mm  
5°  
4mm  
1.25mm

Healing cap Regular

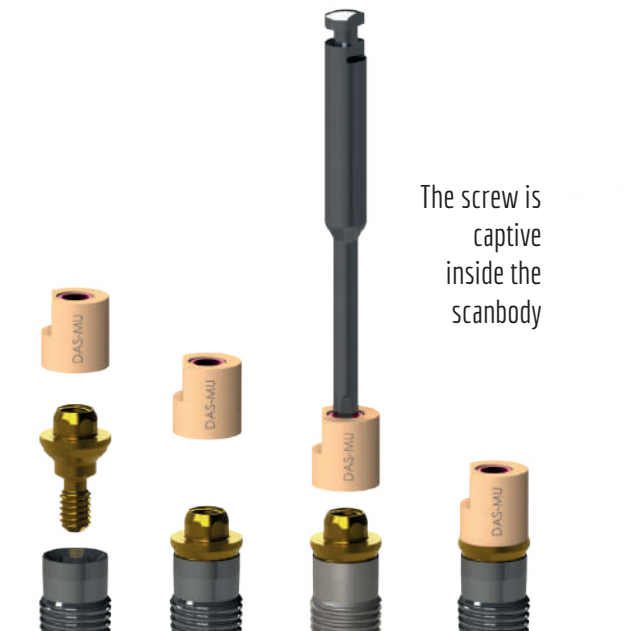
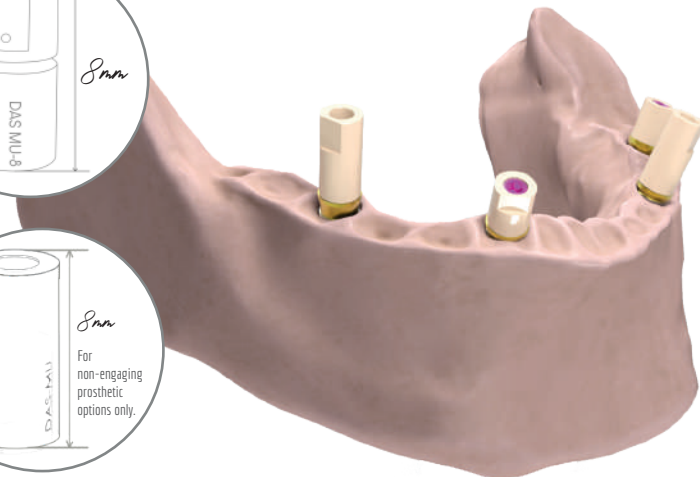
4mm  
15°  
4.8mm  
0.50mm  
4mm

Healing cap Wide

# MULTI-UNIT SCANBODY



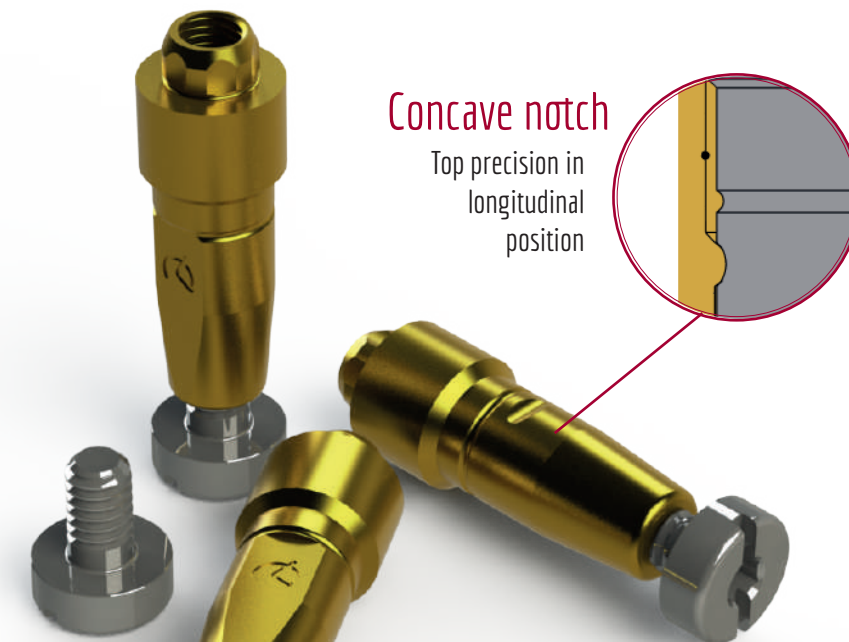
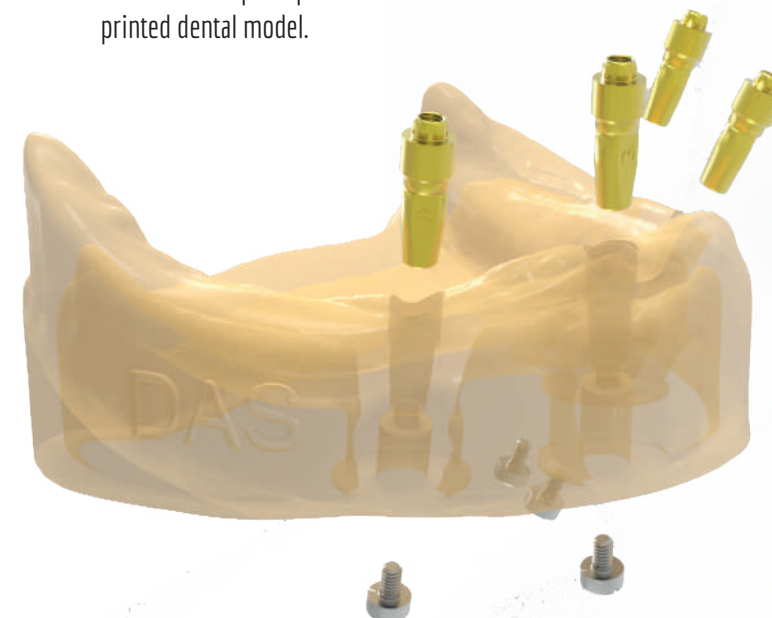
3 different scanbodies available in order to choose in which situation is better to use 4,5mm, 8mm or Dynamic μScanbody with magnet system.



The screw is captive inside the scanbody

# DIGITAL ANALOG

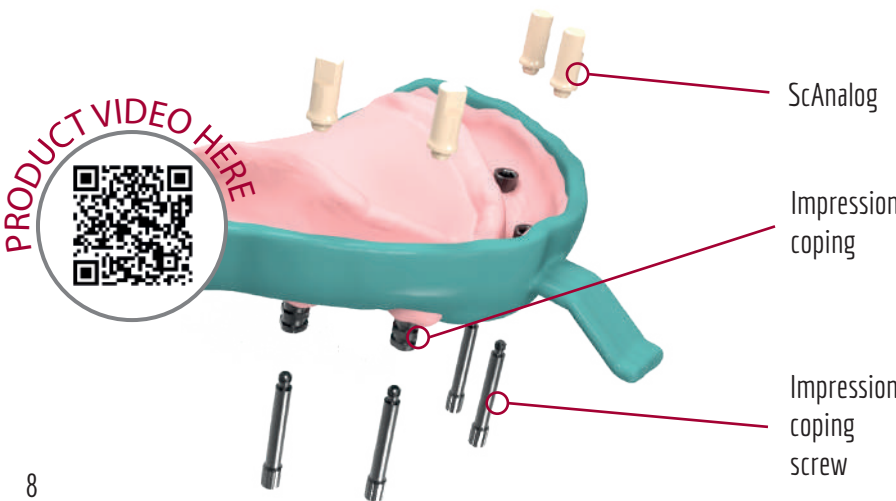
Digital analog of the dental implant to simulate implant position in a 3D printed dental model.



**Concave notch**  
Top precision in longitudinal position

**Screwed fastening**  
Prevents the analog from moving in Z

# MULTI-UNIT SCANALOG



ScAnalog

Impression coping

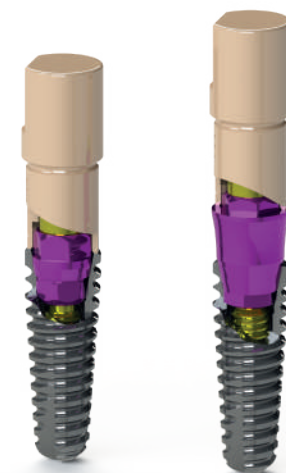
Impression coping screw

# DYNAMIC μSCANBODY

All components of the Multi-Unit DAS System can also be used with the Dynamic μScanbody to scan direct to implant and select virtually the ideal gingival height Multi-unit.

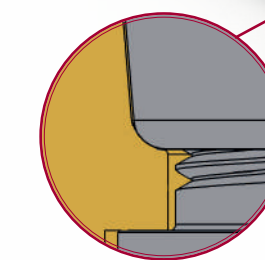
You can scan with the Dynamic μScanbody and then use the special Dynamic μScanbody library with the MU components.

For non-engaging prosthetic options only.

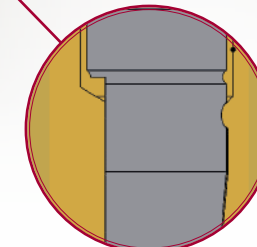


# ANALOG

Also available traditional analog for plaster model.



**Curved Surface**  
Accuracy of orientation guaranteed



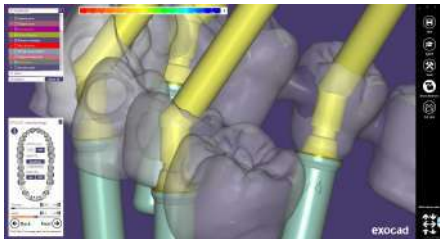
**Longitudinal cut**  
Longitudinal cut to avoid rotation X-Y

# DYNAMIC TIBASE®

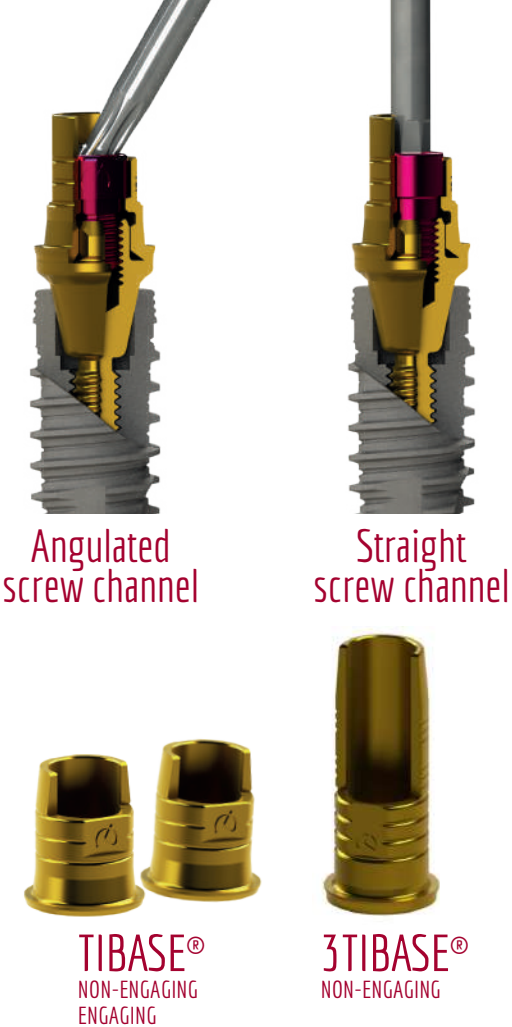
To correct  
**ANGULATION** up to  
**45°**



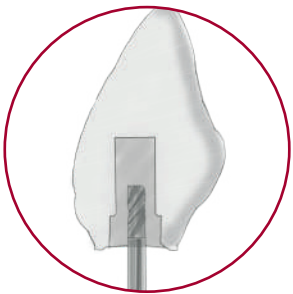
## CAD DESIGN



DAS Multi-U nit system **allows** to **change** the **MU** in the **library** without rescanning or redesigning the case. That facilitates the lab and clinic work, as technician can change the MU without the need to make a new appointment with the patient to re-scan.  
**If we make a NR case, the option of changing MU is not allow in the design.**



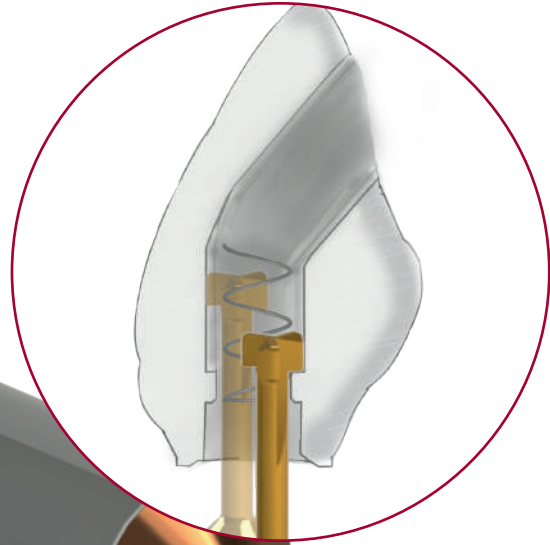
# DIRECT TO IMPLANT (One piece)



**Step 1**  
Crown with  
pre drill



**Step 2**  
Crown with  
angled chanel



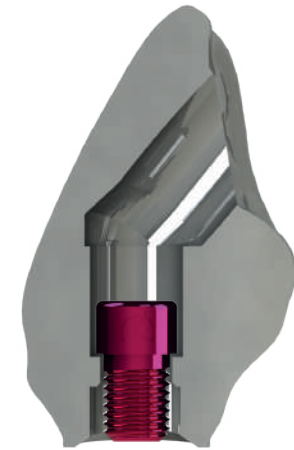
**Step 3**  
**DMTONE**  
Crown with Dynamic Milling Tool.  
Milling the screw seat and  
increasing the diameter of the  
straight channel.



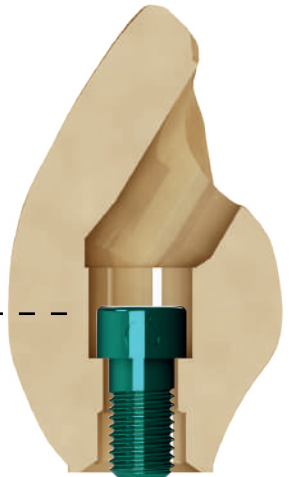
Dynamic  
screw



Provisional (temporary)  
Dynamic screw



Final restorations 0-45°  
Direct to implant libraries available R/NR



Greater seating  
thickness  
Greater contact surface  
between the screw and  
the material for greater  
safety in soft materials.

Provisional (temporary) restorations up to 35°

Provisional (temporary) Direct to implant libraries available R/NR

# DAS MU LIBRARIES



**MU Scanbody**  
DAS\_MU\_4.5\_XXXX\*\_PREMIUM  
DAS\_MU\_8\_XXXX\*\_PREMIUM  
DAS\_MU\_DS8\_XXXX\*\_PREMIUM



**MU ScAnalog**  
DAS\_MU\_SA\_XXXX\*\_PREMIUM



**Dynamic μScanbody**  
DAS\_MU\_I/IG\_XXXX\*\_PREMIUM

\*XXXX= compatibility code

# MU DAS SYSTEM COMPONENTS



**Ratchet**  
49.409.000.01-2



**Screwdriver**  
43.321.316.01-2



**Healing Cap Regular**  
40.320.003.98-2



40.320.003.88-2 (Captive screw)



**Healing Cap Wide**  
40.320.003.99-2



40.320.003.89-2 (Captive screw)



**Impression coping**  
29.301.000.10-2 (Engaging)  
29.301.000.11-2 (Non-engaging)



**Analog**  
22.612.209.01-2



**Titanium Abutment**  
35.312.209.21-2



**Digital Analog**  
34.312.209.01-2



**MU Scanbody 4,5mm**  
53.412.209.01-2



**MU Scanbody 8mm**  
53.422.209.02-2 (R)



**MU Dynamic μScanbody**  
52.418.137.01-2



**Screwdriver adaptor**  
43.621.410.01-2  
43.624.410.01-2  
43.630.410.01-2



**MU ScAnalog**  
23.412.209.01-2



**MU Dynamic TiBase®**  
31.312.209.01-2 (Engaging)



31.322.209.01-2 (Non-engaging)



**MU Dynamic 3TiBase®**  
31.322.209.21-2 (Non-engaging)



**Dynamic Screw**  
41.320.040.01-2



**Provisional (temporary) Dynamic Screw**  
41.320.050.02-2



**Straight Screw**  
40.320.003.06-2



**Dynamic Screwdriver**  
43.618.201.01-2 (18mm)  
43.624.201.01-2 (24mm)  
43.632.201.01-2 (32mm)



**Screwdriver Hex.1,2**  
43.601.103.02-2



**MU DMTone**  
33.390.716.01-2 Shank Ø3  
33.490.716.01-2 Shank Ø4  
33.690.716.01-2 Shank Ø6